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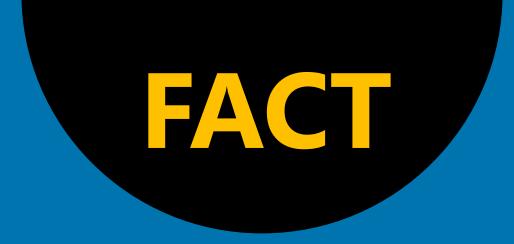
Presentation Overview



RGB-D

Basic Definitions:





RGB cameras are getting incredibly small

Form Factor



Initial Results

Point measurements on an obstacle





Work to be done

Critical parts that need to be developed and tested

Various lighting conditions

[outdoors, indoors, low light etc.]

Noise reduction

[reflections]

Voice guide

[measurements to speech]

Learning

[recognize and categorize obstacles]

