# hack4glarus-2019-summer - Task #6761

## Slides which don't fit any issue

06/02/2019 04:21 PM - Axel Beckert

| Status:         | Closed           | Start date:     | 06/02/2019 |
|-----------------|------------------|-----------------|------------|
| Priority:       | Low              | Due date:       |            |
| Assignee:       | Nico Schottelius | % Done:         | 0%         |
| Category:       |                  | Estimated time: | 0.00 hour  |
| Target version: |                  |                 |            |
| PM Check date:  |                  |                 |            |

## Description

Slides double-p and XTaran got for presentation but don't fit any issue so far.

## History

#### #1 - 06/02/2019 04:22 PM - Axel Beckert

- File drone deployment system.pdf added
- File Deapth\_AM.pdf added
- File 2way\_wan\_opt.pdf added

#### #2 - 06/02/2019 08:43 PM - Nico Schottelius

- Status changed from New to Resolved

Thanks everyone for participating! It was great seeing all of you!

#### #3 - 06/02/2019 08:47 PM - Nico Schottelius

- Status changed from Resolved to Closed

Thanks!

## #4 - 10/03/2019 10:45 PM - II nu

The drone deployment slide is interesting.

a fixed wing uav can do around 3-4 hours or more depending on the weight  $% \left\{ 1\right\} =\left\{ 1\right\} =\left$ 

radio is an issue especially in the mountains, however the problem is more complex. we have to first decide what data do we require: telemetry, remote control, remote waypoint setting, live video feed, what kind of video feed, any extra sensors (heat camera forexample). depending on the requirements then we can choose a frequency.

rule of thumbs: higher frequency has higher the bandwidth and lower range.

mountains are also tricky

if you dont want to climb the mountains, you could have a drone hovering over you at a height to overcome the line of sight issues, but im not sure how it works in reality

then the problem is the camera. it cant match the eye on a live feed.

if you want to cover big areas, then you will need a huge mesh of drones, and autopilot which handles signal loss, or a complete autopilot which completes a preprogrammed "blind" route or a more advanced one which analyses video feed (its need a lot of power afaik) / sensors and makes decisions on their own, but i dont know a lot about it

sateillites could help solve some issues but the latency would be huge

regulations are hard, aviation is a huge business, not so much civil stuff going on.. it doesnt help future to happen easily

## **Files**

| drone deployment system.pdf | 756 KB  | 06/02/2019 | Axel Beckert |
|-----------------------------|---------|------------|--------------|
| 2way_wan_opt.pdf            | 41.5 KB | 06/02/2019 | Axel Beckert |
| Deapth_AM.pdf               | 1.77 MB | 06/02/2019 | Axel Beckert |

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